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to ensure this controlled stop.

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This unit also covers robot safety.  
Moving the Robot. Students begin  
this unit in the classroom,

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learning how to interpret messages on the pendant and select operating modes. KUKA robots have four operating modes: T1 (Manual Reduced Velocity) This mode is for test operation. The robot moves at a maximum velocity of 250mm/s.



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This mode allows jogging.

~~What I Learned at KUKA College:  
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1. Connect the 4 pin M8 cable (5m long) to the sensor and secure it to the robot with cable ties. Make sure that enough extra

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cable length is available around the joints for bending. 2. Place the converter somewhere near the KUKA robot control cabinet and connect the 4 pin M8 sensor cable. 3.

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Applying/Painting/Glueing Arc  
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other areas Cutting/Separation  
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instructions Calculated positions  
KUKA IDE (Integrated  
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robot Tool calibration and  
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In mode Working with variables

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The outstanding kinematic and safety-relevant functions of the KUKA KR C4 controller remain fully available since the

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mxAutomation command interpreter of the KR C4 communicates the PLC commands to the path planning module, which sets the robot in motion with the accustomed precision and reliability.

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