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1+ k. 2)(Q+ bsin(!t))2(54) The Hamiltonian is now explicitly dependent on time, and hence is not conserved, as is con rmed by the fact that dH=dt6= 0. The energy is given by E= T+ V = 1 2 (Q_ + b!cos(!t))2+ 1 2 (k. 1+ k. 2)(Q+ b!sin(!t))2(55) So, dE dt = m(Q_ + b!cos(!t))(Q b!2sin(!t)) + (k. 1+ k.

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Solutions Goldstein Chapter 9. CHAPTER 9 – CANONICAL TRANSFORMATIONS DERIVATIONS: 9.4. Show directly that the transformation is canonical. 9.4. Sol. We are given a transformation as follows, We know that the fundamental Poisson Brackets of the transformed variables have the same value when evaluated with respect to any canonical coordinate set.

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We use the first constraint to solve for the coordinate r: r = R + a, r? = r¨ = 0. We use this solution in Lagrange’s equations for r, ?: ?m(R + a)??2 + mg sin ? = ? m(R + a)2 ?¨ + mg(R + a) cos ? = µ(R + a) (6) (7) We use the rolling constraint to find an expression for ? as a function of ?: ?=? a+R ? + ?0 a (8)